## 1 Microsecond Precision Sample and Hold Amplifier

The HA-5320 was designed for use in precision, high speed data acquisition systems.

The circuit consists of an input transconductance amplifier capable of providing large amounts of charging current, a low leakage analog switch, and an output integrating amplifier. The analog switch sees virtual ground as its load; therefore, charge injection on the hold capacitor is constant over the entire input/output voltage range. The pedestal voltage resulting from this charge injection can be adjusted to zero by use of the offset adjust inputs. The device includes a hold capacitor. However, if improved droop rate is required at the expense of acquisition time, additional hold capacitance may be added externally.

This monolithic device is manufactured using the Intersil Dielectric Isolation Process, minimizing stray capacitance and eliminating SCRs. This allows higher speed and latchfree operation. For further information, please see Application Note AN538.

## Pinouts




## Features

- Gain, DC . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $2 \times 10^{6}$ V/V
- Acquisition Time . . . . . . . . . . . . . . . . . . . . . .1.0 $\mu \mathrm{s}$ (0.01\%)
- Droop Rate. . . . . . . . . . . . . . . . . . . . $0.08 \mu \mathrm{~V} / \mu \mathrm{s}\left(+25^{\circ} \mathrm{C}\right)$ $17 \mu \mathrm{~V} / \mu \mathrm{s}$ (Full Temperature)
- Aperture Time. . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 25ns
- Hold Step Error (See Glossary) 5 mV
- Internal Hold Capacitor
- Fully Differential Input
- TTL Compatible
- Pb-Free Available (RoHS Compliant)


## Applications

- Precision Data Acquisition Systems
- Digital to Analog Converter Deglitcher
- Auto Zero Circuits
- Peak Detector


## Ordering Information

| PART <br> NUMBER | PART <br> MARKING | TEMP. <br> RANGE <br> ( $\left.{ }^{\circ} \mathrm{C}\right)$ | PACKAGE | PKG. <br> DWG. \# |
| :--- | :---: | :---: | :--- | :--- |
| HA1-5320-2 | HA1-5320-2 | -55 to +125 | 14 Ld CERDIP | F14.3 |
| HA1-5320-5 | HA1-5320-5 | 0 to +75 | 14 Ld CERDIP | F14.3 |
| HA9P5320-5Z <br> (Note) | HA9P5320-5Z | 0 to +75 | 16 Ld SOIC <br> (Pb-free) | M16.3 |

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100\% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb -free soldering operations. Intersil Pb -free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb -free requirements of IPC/JEDEC J STD-020.

Functional Diagram


## Absolute Maximum Ratings

Supply Voltage . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 40 V
Differential Input Voltage . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 24 V
Digital Input Voltage . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . +8V, -15V
Output Current, Continuous (Note 1) . . . . . . . . . . . . . . . . . . . $\pm 20 \mathrm{~mA}$

## Operating Conditions

Temperature Range
HA-5320-2 . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $-55^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$
HA-5320-5 . . . . . . . . . . . . . . . $0^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$
Supply Voltage Range (Typical, Note 2) . . . . . . . . $\pm 13.5 \mathrm{~V}$ to $\pm 20 \mathrm{~V}$

## Thermal Information

| , | $\theta_{J A}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$ | $\theta_{\mathrm{JC}}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$ |
| :---: | :---: | :---: |
| CERDIP Package | 70 | 18 |
| SOIC Package | 90 | N/A |
| Maximum Junction Temperature (Ceramic Package) |  |  |
| Maximum Junction Temperature (Plastic Package) |  |  |
| Maximum Storage Temperature Range . . . . . . . . . -65 ${ }^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ |  |  |
| Maximum Lead Temperature (Soldering 10s) . . . . . . . . . . . . $300^{\circ} \mathrm{C}$ (SOIC - Lead Tips Only) |  |  |
| Pb-Free Reflow Profilesee link below http://www.intersil.com/pbfree/Pb | flow.asp |  |

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTES:

1. Internal Power Dissipation may limit Output Current below 20mA.
2. Specification based on a one time characterization. This parameter is not guaranteed.
3. $\theta_{\mathrm{JA}}$ is measured with the component mounted on an evaluation PC board in free air.

Electrical Specifications $\quad \mathrm{V}_{\text {SUPPLY }}= \pm 15.0 \mathrm{~V} ; \mathrm{C}_{\mathrm{H}}=$ Internal; Digital Input: $\mathrm{V}_{\mathrm{IL}}=+0.8 \mathrm{~V}$ (Sample), $\mathrm{V}_{\mathrm{IH}}=+2.0 \mathrm{~V}$ (Hold), Unity Gain Configuration (Output tied to -Input), Unless Otherwise Specified

| PARAMETER | TEST CONDITIONS | TEMP. ( ${ }^{\circ} \mathrm{C}$ ) | HA-5320-2 |  |  | HA-5320-5 |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX | MIN | TYP | MAX |  |
| INPUT CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Input Voltage Range |  | Full | $\pm 10$ | - | - | $\pm 10$ | - | - | V |
| Input Resistance |  | 25 | 1 | 5 | - | 1 | 5 | - | $\mathrm{M} \Omega$ |
| Input Capacitance |  | 25 | - | - | 5 | - | - | 5 | pF |
| Offset Voltage |  | 25 | - | 0.2 | - | - | 0.5 | - | mV |
|  |  | Full | - | - | 2.0 | - | - | 1.5 | mV |
| Bias Current |  | 25 | - | 70 | 200 | - | 100 | 300 | nA |
|  |  | Full | - | - | 200 | - | - | 300 | nA |
| Offset Current |  | 25 | - | 30 | 100 | - | 30 | 300 | nA |
|  |  | Full | - | - | 100 | - | - | 300 | nA |
| Common Mode Range |  | Full | $\pm 10$ | - | - | $\pm 10$ | - | - | V |
| CMRR | $\mathrm{V}_{\mathrm{CM}}= \pm 5 \mathrm{~V}$ | 25 | 80 | 90 | - | 72 | 90 | - | dB |
| Offset Voltage Temperature Coefficient |  | Full | - | 5 | 15 | - | 5 | 20 | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| TRANSFER CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Gain | DC, (Note 12) | 25 | $10^{6}$ | $2 \times 10^{6}$ | - | $3 \times 10^{5}$ | $2 \times 10^{6}$ | - | V/V |
| Gain Bandwidth Product ( $A_{V}=+1$, Note 5) | $\mathrm{C}_{\mathrm{H}}=100 \mathrm{pF}$ | 25 | - | 2.0 | - | - | 2.0 | - | MHz |
|  | $\mathrm{C}_{\mathrm{H}}=1000 \mathrm{pF}$ | 25 | - | 0.18 | - | - | 0.18 | - | MHz |
| OUTPUT CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Output Voltage |  | Full | $\pm 10$ | - | - | $\pm 10$ | - | - | V |
| Output Current |  | 25 | $\pm 10$ | - | - | $\pm 10$ | - | - | mA |
| Full Power Bandwidth | Note 4 | 25 | - | 600 | - | - | 600 | - | kHz |
| Output Resistance | Hold Mode | 25 | - | 1.0 | - | - | 1.0 | - | $\Omega$ |
| Total Output Noise (DC to 10MHz) | Sample | 25 | - | 125 | 200 | - | 125 | 200 | $\mu \mathrm{V}_{\mathrm{RMS}}$ |
|  | Hold | 25 | - | 125 | 200 | - | 125 | 200 | $\mu \mathrm{V}_{\mathrm{RMS}}$ |

## Electrical Specifications

$\mathrm{V}_{\text {SUPPLY }}= \pm 15.0 \mathrm{~V} ; \mathrm{C}_{\mathrm{H}}=$ Internal; Digital Input: $\mathrm{V}_{\mathrm{IL}}=+0.8 \mathrm{~V}$ (Sample), $\mathrm{V}_{\mathrm{IH}}=+2.0 \mathrm{~V}$ (Hold), Unity Gain Configuration (Output tied to -Input), Unless Otherwise Specified (Continued)

| PARAMETER | TEST CONDITIONS | TEMP. ( $\left.{ }^{\circ} \mathrm{C}\right)$ | HA-5320-2 |  |  | HA-5320-5 |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX | MIN | TYP | MAX |  |
| TRANSIENT RESPONSE |  |  |  |  |  |  |  |  |  |
| Rise Time | Note 5 | 25 | - | 100 | - | - | 100 | - | ns |
| Overshoot | Note 5 | 25 | - | 15 | - | - | 15 | - | \% |
| Slew Rate | Note 6 | 25 | - | 45 | - | - | 45 | - | V/ $/ \mathrm{s}$ |
| DIGITAL INPUT CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | Full | 2.0 | - | - | 2.0 | - | - | V |
|  | $\mathrm{V}_{\text {IL }}$ | Full | - | - | 0.8 | - | - | 0.8 | v |
| Input Current | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 25 | - | - | 4 | - | - | 4 | $\mu \mathrm{A}$ |
|  |  | Full | - | - | 10 | - | - | 10 | $\mu \mathrm{A}$ |
|  | $\mathrm{V}_{\mathrm{IH}}=+5 \mathrm{~V}$ | Full | - | - | 0.1 | - | - | 0.1 | $\mu \mathrm{A}$ |
| SAMPLE AND HOLD CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Acquisition Time (Note 7) | To 0.1\% | 25 | - | 0.8 | 1.2 | - | 0.8 | 1.2 | $\mu \mathrm{s}$ |
|  | To 0.01\% | 25 | - | 1.0 | 1.5 | - | 1.0 | 1.5 | $\mu \mathrm{s}$ |
| Aperture Time (Note 8) |  | 25 | - | 25 | - | - | 25 | - | ns |
| Effective Aperture Delay Time |  | 25 | -50 | -25 | 0 | -50 | -25 | 0 | ns |
| Aperture Uncertainty |  | 25 | - | 0.3 | - | - | 0.3 | - | ns |
| Droop Rate |  | 25 | - | 0.08 | 0.5 | - | 0.08 | 0.5 | $\mu \mathrm{V} / \mu \mathrm{s}$ |
|  |  | Full | - | 17 | 100 | - | 1.2 | 100 | $\mu \mathrm{V} / \mu \mathrm{s}$ |
| Drift Current | Note 9 | 25 | - | 8 | 50 | - | 8 | 50 | pA |
|  |  | Full | - | 1.7 | 10 | - | 0.12 | 10 | nA |
| Charge Transfer | Note 9 | 25 | - | 0.5 | 1.1 | - | 0.5 | 1.1 | pC |
| Hold Step Error | Note 9 | 25 | - | 5 | 11 | - | 5 | 11 | mV |
| Hold Mode Settling Time | To 0.01\% | Full | - | 165 | 350 | - | 165 | 350 | ns |
| Hold Mode Feedthrough | $10 V_{\text {P-p, }} 100 \mathrm{kHz}$ | Full | - | 2 | - | - | 2 | - | mV |
| POWER SUPPLY CHARACTERISTICS |  |  |  |  |  |  |  |  |  |
| Positive Supply Current | Note 10 | 25 | - | 11 | 13 | - | 11 | 13 | mA |
| Negative Supply Current | Note 10 | 25 | - | -11 | -13 | - | -11 | -13 | mA |
| Supply Voltage Range | Note 2 |  | $\pm 13.5$ | - | $\pm 20$ | $\pm 13.5$ | - | $\pm 20$ | V |
| Power Supply Rejection | V+, Note 11 | Full | 80 | - | - | 80 | - | - | dB |
|  | V-, Note 11 | Full | 65 | - | - | 65 | - | - | dB |

## NOTES:

4. $\mathrm{V}_{\mathrm{O}}=20 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega ; \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} ;$ unattenuated output.
5. $V_{O}=200 \mathrm{mV} V_{P-P} ; R_{L}=2 k \Omega ; C_{L}=50 \mathrm{pF}$.
6. $\mathrm{V}_{\mathrm{O}}=20 \mathrm{~V}$ Step; $\mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega ; \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$.
7. $\mathrm{V}_{\mathrm{O}}=10 \mathrm{~V}$ Step; $\mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega ; \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$.
8. Derived from computer simulation only; not tested.
9. $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=+3.5 \mathrm{~V}, \mathrm{t}_{\mathrm{R}}<20 \mathrm{~ns}\left(\mathrm{~V}_{\mathrm{IL}}\right.$ to $\left.\mathrm{V}_{\mathrm{IH}}\right)$.
10. Specified for a zero differential input voltage between +IN and -IN. Supply current will increase with differential input (as may occur in the Hold mode) to approximately $\pm 46 \mathrm{~mA}$ at 20 V .
11. Based on a 1 V delta in each supply, i.e. $15 \mathrm{~V} \pm 0.5 \mathrm{~V}$ DC .
12. $R_{L}=1 \mathrm{k} \Omega, C_{L}=30 \mathrm{pF}$.

## Test Circuits and Waveforms



FIGURE 1. CHARGE TRANSFER AND DRIFT CURRENT


NOTES:
13. Observe the "hold step" voltage $\mathrm{V}_{\mathrm{P}}$.
14. Compute charge transfer: $\mathrm{Q}=\mathrm{V}_{\mathrm{P}} \mathrm{C}_{\mathrm{H}}$.


NOTES:
15. Observe the voltage "droop", $\Delta \mathrm{V}_{\mathrm{O}} / \Delta \mathrm{t}$.
16. Measure the slope of the output during hold, $\Delta \mathrm{V}_{\mathrm{O}} / \Delta \mathrm{t}$, and compute drift current: $\mathrm{I}_{\mathrm{D}}=\mathrm{C}_{\mathrm{H}} \Delta \mathrm{V}_{\mathrm{O}} / \Delta \mathrm{t}$.

FIGURE 2. CHARGE TRANSFER TEST
FIGURE 3. DRIFT CURRENT TEST


NOTE:
Feedthrough in
$\mathrm{dB}=20 \log \frac{\mathrm{~V}_{\mathrm{OUT}}}{\mathrm{V}_{\mathrm{IN}}}$ where:
$\mathrm{V}_{\text {OUT }}=\mathrm{V}_{\mathrm{P}-\mathrm{P}}$, Hold Mode, $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{P}-\mathrm{P}}$.

FIGURE 4. HOLD MODE FEEDTHROUGH ATTENUATION

## Application Information

The HA-5320 has the uncommitted differential inputs of an op amp, allowing the Sample and Hold function to be combined with many conventional op amp circuits. See the Intersil Application Note AN517 for a collection of circuit ideas.

## Layout

A printed circuit board with ground plane is recommended for best performance. Bypass capacitors $(0.01 \mu \mathrm{~F}$ to $0.1 \mu \mathrm{~F}$, ceramic) should be provided from each power supply terminal to the Supply Ground terminal on pin 13.

The ideal ground connections are pin 6 (SIG. Ground) directly to the system Signal Ground, and pin 13 (Supply Ground) directly to the system Supply Common.

## Hold Capacitor

The HA-5320 includes a 100pF MOS hold capacitor, sufficient for most high speed applications (the Electrical Specifications section is based on this internal capacitor).

Additional capacitance may be added between pins 7 and 11. This external hold capacitance will reduce droop rate at the expense of acquisition time, and provide other trade-offs as shown in the Performance Curves.

If an external hold capacitor $\mathrm{C}_{\text {EXT }}$ is used, then a noise bandwidth capacitor of value $0.1 \mathrm{C}_{\text {EXT }}$ should be connected from pin 8 to ground. Exact value and type are not critical.
The hold capacitor $\mathrm{C}_{\text {EXT }}$ should have high insulation resistance and low dielectric absorption, to minimize droop errors. Polystyrene dielectric is a good choice for operating temperatures up to $+85^{\circ} \mathrm{C}$. Teflon® and glass dielectrics offer good performance to $+125^{\circ} \mathrm{C}$ and above.

The hold capacitor terminal (pin 11) remains at virtual ground potential. Any PC connection to this terminal should be kept short and "guarded" by the ground plane, since nearby signal lines or power supply voltages will introduce errors due to drift current.

## Typical Application

Figure 5 shows the HA- 5320 connected as a unity gain noninverting amplifier - its most widely used configuration. As an input device for a fast successive - approximation A/D converter, it offers very high throughput rate for a monolithic IC sample/hold amplifier. Also, the HA-5320's hold step error is adjustable to zero using the Offset Adjust potentiometer, to deliver a 12-bit accurate output from the converter.

The application may call for an external hold capacitor $\mathrm{C}_{\text {EXT }}$ as shown. As mentioned earlier, $0.1 \mathrm{C}_{\mathrm{EXT}}$ is then recommended at pin 8 to reduce output noise in the Hold mode.
The HA-5320 output circuit does not include short circuit protection, and consequently its output impedance remains low at high frequencies. Thus, the step changes in load current which occur during an A/D conversion are absorbed at the S/H output with minimum voltage error. A momentary short circuit to ground is permissible, but the output is not designed to tolerate a short of indefinite duration.

## Glossary of Terms

## Acquisition Time

The time required following a "sample" command, for the output to reach its final value within $\pm 0.1 \%$ or $\pm 0.01 \%$. This is the minimum sample time required to obtain a given accuracy, and includes switch delay time, slewing time and settling time.

## Charge Transfer

The small charge transferred to the holding capacitor from the inter-electrode capacitance of the switch when the unit is switched to the HOLD mode. Charge transfer is directly proportional to sample-to-hold offset pedestal error, where: Charge Transfer $(\mathrm{pC})=\mathrm{C}_{\mathrm{H}}(\mathrm{pF}) \times$ Hold Step Error $(\mathrm{V})$

## Aperture Time

The time required for the sample-and-hold switch to open, independent of delays through the switch driver and input amplifier circuitry. The switch opening time is the interval between the conditions of $10 \%$ open and $90 \%$ open.

## Hold Step Error

Hold Step Error is the output error due to Charge Transfer (see above). It may be calculated from the specified parameter, Charge Transfer, using the following relationship:
Hold Step (V) $=\frac{\text { Charge Transfer (pC) }}{\text { Hold Capacitance ( } \mathrm{pF} \text { ) }}$

## See Performance Curves.

## Effective Aperture Delay Time (EADT)

The difference between the digital delay time from the Hold command to the opening of the S/H switch, and the propagation time from the analog input to the switch.

EADT may be positive, negative or zero. If zero, the S/H amplifier will output a voltage equal to $\mathrm{V}_{I N}$ at the instant the Hold command was received. For negative EADT, the output in Hold (exclusive of pedestal and droop errors) will correspond to a value of $\mathrm{V}_{\mathrm{IN}}$ that occurred before the Hold command.

## Aperture Uncertainty

The range of variation in Effective Aperture Delay Time. Aperture Uncertainty (also called Aperture Delay Uncertainty, Aperture Time Jitter, etc.) sets a limit on the accuracy with which a waveform can be reconstructed from sample data.

## Drift Current

The net leakage current from the hold capacitor during the hold mode. Drift current can be calculated from the droop rate using the formula:

$$
\mathrm{I}_{\mathrm{D}}(\mathrm{pA})=\mathrm{C}_{\mathrm{H}}(\mathrm{pF}) \times \frac{\Delta \mathrm{V}}{\Delta \mathrm{t}}(\mathrm{~V} / \mathrm{s})
$$



FIGURE 5. TYPICAL HA-5320 CONNECTIONS; NONINVERTING UNITY GAIN MODE

## Typical Performance Curves



FIGURE 6. TYPICAL SAMPLE AND HOLD PERFORMANCE AS A FUNCTION OF HOLD CAPACITOR


FIGURE 7. DRIFT CURRENT vs TEMPERATURE


FIGURE 8. OPEN LOOP GAIN AND PHASE RESPONSE


FIGURE 9A. HOLD STEP vs INPUT VOLTAGE
FIGURE 9. TYPICAL SAMPLE-TO-HOLD OFFSET (HOLD STEP) ERROR

## Die Characteristics

DIE DIMENSIONS:
92 mils $\times 152$ mils $\times 19$ mils
METALLIZATION:
Type: Al, 1\% Cu
Thickness: $16 \mathrm{k} \AA \pm 2 \mathrm{k} \AA$

## PASSIVATION:

Type: Nitride $\left(\mathrm{Si}_{3} \mathrm{~N}_{4}\right)$ over Silox $\left(\mathrm{SiO}_{2}, 5 \%\right.$ Phos $)$ Silox Thickness: $12 \mathrm{k} \AA \pm 2 \mathrm{k} \AA$ Nitride Thickness: $3.5 \mathrm{k} \AA$|  |
| :--- |
| $1.5 \mathrm{k} \AA$ |

TRANSISTOR COUNT:
184
SUBSTRATE POTENTIAL:
V-

Metallization Mask Layout
HA-5320


## Ceramic Dual-In-Line Frit Seal Packages (CERDIP)



NOTES:

1. Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark.
2. The maximum limits of lead dimensions $b$ and $c$ or $M$ shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
3. Dimensions b1 and c1 apply to lead base metal only. Dimension $M$ applies to lead plating and finish thickness.
4. Corner leads ( $1, N, N / 2$, and $N / 2+1$ ) may be configured with a partial lead paddle. For this configuration dimension b3 replaces dimension b2.
5. This dimension allows for off-center lid, meniscus, and glass overrun.
6. Dimension Q shall be measured from the seating plane to the base plane.
7. Measure dimension S1 at all four corners.
8. N is the maximum number of terminal positions.
9. Dimensioning and tolerancing per ANSI Y14.5M-1982.
10. Controlling dimension: INCH .

F14.3 MIL-STD-1835 GDIP1-T14 (D-1, CONFIGURATION A) 14 LEAD CERAMIC DUAL-IN-LINE FRIT SEAL PACKAGE

| SYMBOL | INCHES |  | MILLIMETERS |  | NOTES |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |  |
| A | - | 0.200 | - | 5.08 | - |
| b | 0.014 | 0.026 | 0.36 | 0.66 | 2 |
| b1 | 0.014 | 0.023 | 0.36 | 0.58 | 3 |
| b2 | 0.045 | 0.065 | 1.14 | 1.65 | - |
| b3 | 0.023 | 0.045 | 0.58 | 1.14 | 4 |
| c | 0.008 | 0.018 | 0.20 | 0.46 | 2 |
| c1 | 0.008 | 0.015 | 0.20 | 0.38 | 3 |
| D | - | 0.785 | - | 19.94 | 5 |
| E | 0.220 | 0.310 | 5.59 | 7.87 | 5 |
| e | 0.10 | SC |  | BSC | - |
| eA | 0.30 | SC |  | BSC | - |
| eA/2 | 0.15 | SC |  | BSC | - |
| L | 0.125 | 0.200 | 3.18 | 5.08 | - |
| Q | 0.015 | 0.060 | 0.38 | 1.52 | 6 |
| S1 | 0.005 | - | 0.13 | - | 7 |
| $\alpha$ | $90^{\circ}$ | $105^{\circ}$ | $90^{\circ}$ | $105^{\circ}$ | - |
| aaa | - | 0.015 | - | 0.38 | - |
| bbb | - | 0.030 | - | 0.76 | - |
| ccc | - | 0.010 | - | 0.25 | - |
| M | - | 0.0015 | - | 0.038 | 2, 3 |
| N | 14 |  | 14 |  | 8 |

## Small Outline Plastic Packages (SOIC)



NOTES:

1. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication Number 95.
2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
3. Dimension "D" does not include mold flash, protrusions or gate burrs. Mold flash, protrusion and gate burrs shall not exceed 0.15 mm ( 0.006 inch) per side.
4. Dimension " $E$ " does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25 mm ( 0.010 inch ) per side.
5. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
6. " $L$ " is the length of terminal for soldering to a substrate.
7. " N " is the number of terminal positions.
8. Terminal numbers are shown for reference only.
9. The lead width " $B$ ", as measured 0.36 mm ( 0.014 inch ) or greater above the seating plane, shall not exceed a maximum value of $0.61 \mathrm{~mm}(0.024$ inch)
10. Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.

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